

Optimal Execution Tracking a Benchmark

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Optimal Execution Market Set-Up

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Goal: sell $v > 0$ shares by time $T > 0$ (finite horizon)

- ▶ P_t **mid-price** (unaffected price),

$$P_t = P_0 + \int_0^t \sigma(u) dW_u, \quad 0 \leq t \leq T,$$

- ▶ $V(t)$ volume traded in the market up to (and including) time t
- ▶ Market **VWAP** = $\frac{1}{V} \int_0^T P_t dV(t)$
- ▶ Fraction of shares still to be executed in the market

$$X(t) = \frac{V - V(t)}{V} = \frac{T - t}{T}$$

(deterministic $V(t)$ used to **change clock**). **Convenient simplification** !

Broker Problem

v_t volume executed by the broker up to time t

$$x_t = \frac{v - v_t}{v}$$

fraction of shares left to be executed by the broker at time t

$$x_t = 1 - \ell_t - m_t$$

Where

- ▶ ℓ_t **cumulative** volume executed through **limit orders**
- ▶ m_t **cumulative** volume executed through **market orders**
- ▶ Broker average liquidation price **vwap** = $\frac{1}{v} \int_0^T \left(P_t - \frac{s}{2} \right) dm_t + \left(P_t + \frac{s}{2} \right) d\ell_t$
- ▶ **Objective:** Minimize discrepancy between **vwap** and **VWAP**

Naive Model for the Dynamics of the Order Book

Controls of the broker:

- ▶ $(m_t)_{0 \leq t \leq T}$ **non-decreasing** adapted process
- ▶ $(L_t)_{0 \leq t \leq T}$ **predictable** process

$$\ell_t = \int_0^t \int_{[0,1]} y \wedge L_u \mu(du, dy) = \sum_{i=1}^{N_t} Y_i \wedge L_{\tau_i}$$

where

$$\mu(du, dy)$$

point measure (Poisson) compensator $\nu_t(du)\nu(t)dt$.

$$x_t = 1 - \int_0^t \int_{[0,1]} y \wedge L_u \mu(du, dy) - m_t = 1 - \sum_{i=1}^{N_t} Y_i \wedge L_{\tau_i} - m_t$$

So the dynamics of x_t are given by

$$dx_t = - \int_{[0,1]} y \wedge L_t \mu(dt, dy) - dm_t,$$

with initial condition $x_{0-} = 1$.

Optimization Problem

Goal of the broker

$$\sup_{(\underline{L}, \underline{m}) \in \mathcal{A}} \mathbb{E} \left[U(\text{vwap} - \text{VWAP}) \right],$$

For the CARA exponential utility, approximately

$$\inf_{(\underline{L}, \underline{m}) \in \mathcal{A}} \mathbb{E} \left[\exp \left(-\gamma \left(\frac{S}{2} + \int_0^T [x_u^{L,m} - X(u)] dP_u - S m_u \right) \right) \right],$$

We will work with a **Mean - Variance** criterion

$$\inf_{(\underline{L}, \underline{m}) \in \mathcal{A}} \mathbb{E} \left[\int_0^T \gamma \frac{\sigma(u)^2}{2} [x_u^{L,m} - X(u)]^2 du + S m_T \right],$$

- ▶ S spread
- ▶ $X(u) = (T - u)/T$ fraction of shares left to be executed in the market.

Stochastic Control Problem

Singular control problem of a pure jump process

Value function

$$J(t, x) = \inf_{(\underline{L}, \underline{m}) \in \mathcal{A}(t, x)} J(t, x, \underline{L}, \underline{m})$$

where

$$J(t, x, \underline{L}, \underline{m}) = \mathbb{E} \left[\int_t^T \gamma \frac{\sigma(u)^2}{2} [x_u^{\underline{L}, \underline{m}} - X(u)]^2 du + S m_T \right].$$

$J(t, x)$ is non-decreasing in t for $x \in [0, 1]$ fixed. ($\mathcal{A}(t_2, x) \subset \mathcal{A}(t_1, x)$ whenever $t_1 \leq t_2$)

Tough Luck: Problem is NOT Convex

The set \mathcal{A} of admissible controls is not convex.

For any number $\ell \in (0, 1)$, the two controls $(\underline{L}^1, \underline{m}^1)$ and $(\underline{L}^2, \underline{m}^2)$ by:

$$L_t^1 = \mathbf{1}_{\{t \leq \tau_1\}} + \sum_{k=2}^{\infty} x_{\tau_{k-1}} \mathbf{1}_{\{\tau_{k-1} < t \leq \tau_k\}}, \quad \text{and} \quad m_t^1 = x_T \mathbf{1}_{\{T \leq t\}},$$

and:

$$L_t^2 = \frac{\ell}{2} \mathbf{1}_{\{t \leq \tau_1\}} + \sum_{k=2}^{\infty} x_{\tau_{k-1}} \mathbf{1}_{\{\tau_{k-1} < t \leq \tau_k\}}, \quad \text{and} \quad m_t^2 = x_T \mathbf{1}_{\{T \leq t\}},$$

are admissible, but the pair $(\underline{L}, \underline{m})$ defined by

$$L_t = \frac{1}{2}(L_t^1 + L_t^2), \quad \text{and} \quad m_t = \frac{1}{2}(m_t^1 + m_t^2),$$

IS NOT

Closest Related Works

- ▶ Poisson random measure $\mu(dt, dy)$ for claim sizes Y_t
- ▶ **insurer** pays $Y_t \wedge \alpha_t$ up to a **retention level** α_t
- ▶ **re-insurer** covers the excess $(Y_t - \alpha_t)^+$

Wealth process of the Insurance Company

$$X_t = x + \int_0^t p(\alpha_s) ds - \int_0^t y \wedge \alpha_s \mu(ds, dy) - \int_0^t dD_s$$

- ▶ $p(\alpha)$ insurer net premium (after paying the reinsurance company)
- ▶ D_t cumulative dividends paid up to (and including) time t

$$\sup_{(\alpha_t)_t, (D_t)_t} \mathbb{E} \left[\int_0^\tau e^{-ru} dD_u \right]$$

- ▶ time of bankruptcy $\tau = \inf\{t \geq 0; X_t \leq 0\}$

Jeanblanc-Shyryaev (1995) optimal dividend distribution for Wiener process,
Asmussen- Hjgaard-Taksar (1998) optimal dividend distribution for diffusion,
Mnif-Sulem (2005) prove existence and uniqueness of a viscosity solution,
Goreac (2008) multiple contracts

Similarities & Differences

Similarities

- ▶ $\alpha_t \leftrightarrow$ standing limit orders L_t
- ▶ $D_t \leftrightarrow$ cumulative market orders m_t

Differences

- ▶ We work in a **finite horizon** (PDEs instead of ODEs)
- ▶ We use a **Mean - Variance** criterion
- ▶ We exhibit a **classical** solution (as opposed to a viscosity solution)
- ▶ We derive a **system of ODEs** identifying
 - ▶ the value function
 - ▶ the optimal strategy

Technical Assumptions

$\nu_t(dy)\nu(t)dt$ intensity of Poisson measure $\mu(dt, dy)$ with $\nu_t([0, 1]) = 1$.

- ▶ $\int_0^T \sigma(t)^2 dt < \infty$
- ▶ $\sup_{0 \leq t \leq T} \nu(t) < \infty$
- ▶ $t \mapsto \frac{\sigma(t)^2}{\nu(t)} (X(t) - x)$ is increasing for each $x \in [0, 1]$
- ▶ $t \mapsto \frac{1}{\nu(t)} \nu_t(\cdot)$ is decreasing (in the sense of *stochastic dominance*)

Hamilton-Jabobi-Bellman Equation (QVI)

$$\min [A\phi](t, x), \partial_t \phi(t, x) + [B\phi](t, x) = 0.$$

where

$$[A\phi](t, x) = S - \partial_x \phi(t, x)$$

and

$$[B\phi](t, x) = \gamma \frac{\sigma(t)^2}{2} [X(t) - x]^2 + \nu(t) \inf_{0 \leq L \leq x} \int_{[0,1]} [\phi(t, x - y \wedge L) - \phi(t, x)] \nu_t(dy)$$

with terminal condition

$$\phi(T-, x) = Sx, \quad (\text{notice that } \phi(T, x) = 0)$$

and boundary condition:

$$\phi(t, 0) = \int_t^T \frac{\gamma \sigma(u)^2}{2} X(u) du.$$

Classical Solution

Theorem

The value function is the **unique** solution of

$$-J(t, x) = \min \left[\inf_{0 \leq y \leq x} -J(t, x), \right. \\ \left. \gamma \frac{\sigma(t)^2}{2} [X(t) - x]^2 + \nu(t) \int_{[0,1]} [J(t, (x-y) \vee \tilde{L}(t, y)) - J(t, x)] \nu_t(dy) \right]$$

with

$$J(t, 0) = \gamma \int_0^t \frac{\sigma(u)^2}{2} X(u)^2 du, \quad \text{and} \quad J(T, x) = Sx$$

where

$$\tilde{L}(t, x) = \arg \min_{0 \leq y \leq x} J(t, y)$$

- ▶ J is $C^{1,1}$
- ▶ $x \mapsto J(t, x)$ convex for t fixed
- ▶ $t \mapsto J(t, x)$ non-decreasing for x fixed
- ▶ $\partial_x J(t, x) \geq 0$

Free Boundary (No-Trade Region)

$$[0, T] \times [0, 1] = A \cup B \cup C$$

with

- ▶ $A = \{(t, x); \partial_x J(t, x) < 0\} = \{(t, x); 0 \leq t < \tau_\ell(x)\}$
- ▶ $B = \{(t, x); 0 \leq \partial_x J(t, x) \leq S\} = \{(t, x); \tau_\ell(x) \leq t \leq \tau_m(x)\}$
- ▶ $C = \{(t, x); \partial_x J(t, x) = S\} = \{(t, x); \tau_m(x) \leq t\}$

where

- ▶ $\tau_\ell(x) = \inf\{t > 0; \partial_x J(t, x) \geq 0\}$
- ▶ $\tau_m(x) = \inf\{t > 0; \partial_x J(t, x) \geq S\}$

$$\tau_\ell(x) \leq T(1-x) \leq \tau_m(x)$$

Optimal Trading Strategy

- ▶ If $t > \tau_m(x_t)$ i.e. $(t, x_t) \in C$ (never happens)
 - ▶ **place market orders**
 $\Delta m_t > 0$ (just enough to get into B)
- ▶ If $t = \tau_m(x_t)$ i.e. $(t, x_t) \in \partial C$
 - ▶ **place market orders at a rate** $dm_t = -\dot{\tau}_m(x_t)dt$
(just enough so not to exit B)
- ▶ If $\tau_\ell(x_t) \leq t < \tau_m(x_t)$ i.e. $(t, x_t) \in B \cup \partial A$
 - ▶ **place $L_t = x_t - \tilde{L}(t)$ limit orders**
(as much as possible without getting ahead too much)
- ▶ If $t < \tau_\ell(x_t)$ i.e. $(t, x_t) \in A$ (never happens)
 - ▶ **no trade**

Special Case I: Large Fill Distribution

$\nu_t(dy) = \delta_1(dy)$: the crossings, when they occur, fill all the requested limit orders.

Theorem

The value function solves

$$-J(t, x) = \min \left[\inf_{0 \leq y \leq x} -J(t, x), \gamma \frac{\sigma(t)^2}{2} [X(t) - x]^2 + \nu(t)[J(t, \tilde{L}(t, x)) - J(t, x)] \right]$$

with

$$J(t, 0) = \gamma \int_0^t \frac{\sigma(u)^2}{2} X(u)^2 du, \quad \text{and} \quad J(T, x) = Sx$$

Special Case II: Arrival Price Benchmark

This specific model corresponds to the case $X(\tau) = 0$ for all $\tau \in [0, T]$.

Theorem

The value function is the **unique** solution of

$$-J(t, x) = \min \left[\inf_{0 \leq y \leq x} -J(t, x), \gamma \frac{\sigma(t)^2}{2} x^2 + \nu(t) \int_{[0,1]} [J(t, (x-y)^+) - J(t, x)] \nu_t(dy) \right]$$

with

$$J(t, 0) = \gamma \int_0^t \frac{\sigma(u)^2}{2} X(u)^2 du, \quad \text{and} \quad J(T, x) = Sx$$

Special Case III: Stationary Approximation

When (t, x) is far enough from the corners $(0, 1)$ and $(T, 0)$, J looks like a function of $x - X(t)$ (**deviation from the benchmark**).

Stationarity assumption

- ▶ $\nu_1(dt) = \lambda dt$ for some constant $\lambda > 0$
- ▶ $\nu_t(dy) = \nu(dy)$ for all $t \in [0, T]$.
- ▶ $\sigma(t) = \sigma$ for all $t \in [0, T]$

Look for an approximation of the form

$$J(t, x) \approx \alpha + \beta x + w(x - X(t))$$

for some function w to be determined.

True in the **Large Fill case** (use the Lambert function)

The Discrete Case and Approximation Results

- ▶ The **integer** ν denotes the quantity of shares (expressed as a number of lots) the broker has to sell by time T ,
- ▶ Trades can only be in multiples of one lot.
- ▶ $t \mapsto x_t$ looks like a staircase starting from $x_0 = 1$ and ending at $x_T = 0$.
- ▶ In units of ν lots, the measures $\nu_t(dy)$ are supported by the grid $\{1/\nu, 2/\nu, \dots, (\nu - 1)/\nu, 1\}$
- ▶ The process $\underline{x} = (x_t)_{0 \leq t \leq T}$ and the controls $\underline{L} = (L_t)_{0 \leq t \leq T}$ and $\underline{m} = (m_t)_{0 \leq t \leq T}$ take values in the grid $\mathcal{I}_\nu := \{0, 1/\nu, \dots, (\nu - 1)/\nu, 1\}$.
- ▶ The sets of admissible controls are defined accordingly.
- ▶ Identify functions φ on the grid \mathcal{I}_ν with finite sequence $(\varphi_i)_{0 \leq i \leq \nu}$ where $\varphi_i = \varphi(i/\nu)$.
- ▶ Denote by l_φ the piecewise linear continuous function $[0, 1] \ni x \mapsto [l_\varphi](x)$ which coincides with φ on the grid \mathcal{I}_ν and which is linear on each interval $[i/\nu, (i + 1)/\nu]$.
- ▶ $(\varphi_i)_{0 \leq i \leq \nu}$ is said to be convex if l_φ is convex
- ▶ For any integers ν and ν' , and functions φ and φ' on the grids \mathcal{I}_ν and $\mathcal{I}_{\nu'}$, we have:

$$\|l_\varphi - l_{\varphi'}\|_\infty = \sup_{x \in [0, 1]} |[l_\varphi](x) - [l_{\varphi'}](x)| = \sup_{x \in \mathcal{I}_\nu \cup \mathcal{I}_{\nu'}} |[l_\varphi](x) - [l_{\varphi'}](x)|.$$

Characterization of the Solution

The operators A and B become

$$[A\varphi]_i(t) = S - \varphi_i(t) + \varphi_{i-1}(t), \quad i = 1, \dots, v,$$

and

$$[B\varphi]_i(t) = \gamma \frac{\sigma(t)^2}{2} [X(t) - i/v]^2 + \nu(t) \min_{0 \leq \ell \leq i} \sum_{j=1}^v [\varphi_{i-j \wedge \ell}(t) - \varphi_i(t)] \nu_t(j/v)$$

so the HJB QVI remains the same:

$$\min [[A\varphi]_i(t), \dot{\varphi}_i(t) + [B\varphi]_i(t)] = 0, \quad i = 1, \dots, v.$$

As before we have existence and uniqueness of a C^1 functions of $t \in [0, T]$ satisfying

$$\varphi_i(t) = Si/v + \int_t^T \min_{0 \leq j \leq i} [B\varphi]_j(u) du, \quad i = 0, 1, \dots, v.$$

Interpreting the solution φ as a function on $[0, T] \times \mathcal{I}_v$ defined by $\varphi(t, i/v) = \varphi_i(t)$, since $\varphi_i(T) = Si/v$ and:

$$\dot{\varphi}_i(t) = - \min_{0 \leq j \leq i} [B\varphi]_j(t)$$

we get

$$\dot{\varphi}_i(t) + [B\varphi]_i(t) \geq 0, \quad i = 0, 1, \dots, v$$

and

$$\dot{\varphi}_i(t) = \max_{0 \leq j \leq i} \partial_t \varphi_j(t)$$

so that $i \mapsto \dot{\varphi}_i(t)$ is non-decreasing and

$$-\dot{\varphi}_i(t) = \min \left[\min_{0 \leq j \leq i} -\dot{\varphi}_j(t), [B\varphi]_i(t) \right].$$

Characterization of the Value Function in the Discrete Case

Theorem

The value function J of the problem can be identified to the sequence $(J_i)_{0 \leq i \leq v}$ of C^1 functions of $t \in [0, T]$ satisfying:

$$\left\{ \begin{array}{l} J_0(t) = \int_t^T \frac{\gamma \sigma(u)^2}{2} X(u)^2, \quad J_i(T) = Si/v, \quad i = 0, 1, \dots, v \\ \partial_t J_i(t) = \min \left[\partial_t J_{i-1}(t), \right. \\ \left. \nu(t) \sum_{j=1}^v [\varphi_{(i-j) \vee \tilde{l}_i(t)}(t) - \varphi_i(t)] \nu_t(j) + \frac{\gamma \sigma(t)^2}{2} [X(t) - i/v]^2 \right] \end{array} \right.$$

where

$$\tilde{l}_i(t) = \min\{l; \varphi_l(t) = \min_{0 \leq j \leq i} \varphi_j(t)\}$$

Optimal Solution in the Discrete Case

- ▶ $\tau_i^m = \inf\{t \in [0, T]; J_i(t) - J_{i-1}(t) < S/v\}$
- ▶ $\tau_i^l = \inf\{t \in [0, T]; J_i(t) - J_{i-1}(t) < 0\}$
- ▶ $\tau_i^m \leq T x(i - \frac{1}{2}) < \tau_i^l$